
21st CENTURY SAILING MULTIHULLS

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Errata

Page 9:

$$V_B/V_T = \sin\gamma \operatorname{ctn}\beta - \cos\gamma \quad (1-2)$$

Page 14:

$$V_{B,\max} = \left\{ \left| \left[X^2 / (X^2 + 2X\cos\gamma + 1) \right] \left[2 / (\rho_A C_y) \right] \left[(bW) / (hA_s) \right] \right| \right\}^{1/2} \quad (2-14)$$

Page 15:

$$X^4 - a^2 [C_L \sin\gamma - C_D (X + \cos\gamma)]^2 (X^2 + 2X\cos\gamma + 1) = 0 \quad (2-21)$$

$$V_{B,\max} = \left\{ \left| [(bL)/(\alpha h)] [C_L \sin\gamma - C_D (X + \cos\gamma)] / [(X + \cos\gamma) + C_D \sin\gamma] \right| \right\}^{1/2} \quad (2-22)$$

Line 13, from bottom of page:

The resistance curve for *Tahiti Bill*, a CSK catamaran, suggests $\alpha = 0.031 \text{ ft/kt}^2$.

Page 17:

Line 12, from top of page begins:

where ρ_H is the mass density of the water ...

Page 19:

$$V_W = V_B = \sqrt{\frac{\lambda g}{2\pi}} \quad (3-3)$$

Page 20:

$$\zeta \propto (V_B^2/g) [B/(C_p L)]^2 \quad (3-14)$$

Line 6, from bottom of page:

for $S \geq 1.34 C_p^{1/2}$ and is zero for $S < 1.34 C_p^{1/2}$.

Page 21:

$$\frac{1}{2} B/H = \alpha \quad (3-20)$$

Lines 8 & 9, from bottom of page:

and by using the definition of the displacement-length ratio D , Eq. (3-17), we find ...

Line 4, from bottom of page:

We will divide the hull longitudinally about the maximum section into two semi-hulls of equal volume, but (except for proas) of different lengths ℓ_1 and ℓ_2 .

Page 25:

$$y(x) = \left\{ 2x\ell - x^2 + \left[(\ell^2 - b^2)/(2b) \right]^2 \right\}^{1/2} - (\ell^2 - b^2)/(2b) \quad (3-29)$$

from which

$$V = \frac{\pi}{2\alpha} \int_0^\ell y^2 dx$$

Skip one line, then:

where $\omega = \ell/b$. Then, using ...

Beginning at line 11, from bottom of page:

which is a function only of $\omega = \ell/b$, and is independent of the choice of section shape. This curve is plotted in Fig. 3-8. We see that for values of $\ell/b = L/B$ of interest, say $10 \leq L/B \leq 25$, C_p has a nearly constant value of about 0.534.

Page 27:

Beginning the second sentence after Eq. (3-36):

If we evaluate Eq. (3-36) at $x = \ell$, $y = b$, and define

$$\phi = e^{-a\ell} \quad (3-37)$$

then $b = Y(1-\phi)$, $a = (\ln\phi^{-1})/\ell$, and we can rewrite Eq. (3-36) as

Page 29

Beginning after Eq. (3-45):

For $\phi \leq 0.5$ degree, C_p must be greater than 0.65 for $\ell/b \geq 10$, which does not present a problem.

Line 6, from bottom of page begins:
(3-47) to calculate C_{p2} , ℓ_2 , and ℓ_1 . Our choice ...

Page 31

Line 2, from top of page:
for $C_p \geq 0.70$.

Lines 6 & 7, from top of page:

$$\begin{array}{ll} L = 42 \text{ feet} & C_{p1} = 0.534 \\ C_p = 0.65 & W = 8000 \text{ lbs.} \end{array}$$

Lines 10 & 11:

$$\begin{array}{l} \text{Eq (3-50)} \rightarrow \ell_2 = 16.44 \\ \text{Eq (3-47)} \rightarrow \ell_1 = 25.56 \end{array}$$

Beginning on line 15:

arc waterline, so Eqs. (3-32) to (3-35) are used to calculate A_{w1} , A_{wp1} , ψ_1 , and A_{lp1} respectively, having first used Eq. (3-23) to ascertain B (and $b = \frac{1}{2}B$). Solving Eq. 3-40 for ϕ corresponding to $C_{p2} = 0.83$, we find $\phi = 1.49 \times 10^{-4}$ and proceed to calculate A_{w2} , A_{wp2} , ψ_2 , and A_{lp2} using Eqs. (3-41) to (3-44).

Page 39

Second paragraph, third last line ends:
... at the stall point by a further 25

Page 51

$$\frac{1}{2}\rho_1 A_1 (V_A^2 - V_{A\infty}^2) = \rho_1 A_1 (V_A^2 - V_A V_{A\infty}) (1 - a_1) \quad (5-8)$$

Page 52:

$$P_1 = 2\rho_1 A_1 a_1 (1 - a_1)^2 V_A^3 \quad (5-13)$$

Page 55:

$$V_B/V_T = X ; V_A/V_T = Y ; (\rho_2 A_2)/(\rho_1 A_1) = \mu \quad (5-31)$$

Last paragraph, beginning with the second line:

parameter space, so I have chosen to take $\mu = 1$ in all cases, i.e., $A_1/A_2 = \rho_2/\rho_1 = 837$; I have also chosen ...

Page 56

Top row of top Table 5-2:

CASE I				CASE II			CASE III		
γ	X	a_1	a_2	X	a_1	a_2	X	a_1	a_2

Top row of bottom Table 5-2:

CASE IV				CASE V		
γ	X	a_1	a_2	X	a_1	a_2

Page 57:

$$F_2 = 2\rho_2 A_2 a_2 (1 - a_2) V_B^2 \tag{5-40}$$

$$P_2 = 2\rho_2 A_2 a_2 (1 - a_2)^2 V_B^3 \tag{5-41}$$

Page 58:

Caption for Fig. 5-5:

Fig. 5-5. Polar plot of v_B/v_T as a function of course angle γ for windmill mode cases I - V.

Page 59:

Line 3:

are possible. As before, we will linearize the problem by setting $\eta = \theta = 0$.

Third line after Eq. (5-50):

sufficiently small, or $X < 0$ if μ is sufficiently large. If we include finite θ ,

$$X = \varepsilon / \left[\varepsilon + \mu a_2 - \varepsilon^2 (1 - a_2) \right] \tag{5-52}$$

Page 61:

$$F_2 = 2\rho_1 A_2 a_2 (1 + a_2) V_A^2 \cos^2 \beta \tag{5-58}$$

$$P_2 = 2\rho_1 A_2 a_2 (1 + a_2)^2 V_A^3 |\cos^3 \beta| \quad (5-59)$$

Page 64:

$$V_B/V_T = \left\{ (1+4\theta) - \left[(1+4\theta)^2 - (1+4\theta-4\eta)(1+4\theta) \right]^{1/2} \right\} / (1+4\theta-4\eta); \quad 4\eta < 1+4\theta \quad (5-75)$$

Top row of Table 5-3:

γ	X_I	X_{II}	X_{III}	X_{IV}	X_V
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Page 65:

$$L_H = \frac{1}{2} \rho_h V_B^2 (A_{lp} C_{L,h} + A_k C_{L,k}) \quad (6-1)$$

$$F_y = \frac{1}{2} \rho_a V_A^2 A_s (C_L \cos \beta + C_D \sin \beta) \quad (6-2)$$

Next line begins:

where ρ_h and ρ_a are the mass densities...

Page 71:

Paragraph three, second line, second sentence:

Look to the description of lift production in chapter 7 in terms of the Magnus

Same paragraph, line five:

at right angles to the water velocity vector $-V_B$, and a strong lift is

Last paragraph, first line:

Now let us examine the other type of vertical hydrofoil: rudders. The

Page 77:

Second paragraph, second line:

an angle of attack ϕ to the apparent wind. The rotor produces its lift by

Same paragraph, line four begins:

attack ϕ is taken by the velocity ratio ...

Page 79:

$$U_{\theta} = 0 \quad (7-7)$$

for $\theta = 270^{\circ}$, $r/a + a/r = \alpha$; $\alpha \geq 2$

$$r/a = 1/2 \left[\alpha + (\alpha^2 - 4)^{1/2} \right] ; \alpha \geq 2 \quad (7-8)$$

Page 81:

Paragraph two, last line:

and/or by erecting dams or fences to inhibit the axial flow.

Paragraph three, beginning with line two:

function of $\alpha = v/V$ for various values of aspect ratio, $\lambda = 1/2 \ell/a$. In these experiments there were no fences^[7-3]. In Figs. 7-6 and 7-7, we show the results of experiments on a cylinder of aspect ratio $\lambda = 12$ with fences at

Page 85:

$$N = \rho v V \ell (2a)^3 (\pi^2/R_e) \quad (7-16)$$

Page 87:

Line 9, from top of page:

Using Eqs. (7-13), (7-15), and (7-18) and expressing the length of the rotor ℓ

Line 14, from top of page:

where we have used $\rho = 2.38 \times 10^{-3}$ slugs/ft³ and $\mu = 1.22 \times 10^{-5}$ lb/(ft s)^[7-11]

Page 89:

Line 10, from bottom of page:

how rotor characteristics vary with aspect ratio λ and fence radius ratio κ ;

$$C_D = (A_R C_{D0} + A_p C_{Dp})/A_R \quad (7-24)$$

Page 90:

Table 7-1, top line:

v , rev/s	$\alpha = v/V$	R_e	k_q
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Table 7-2, top line:

f					$A_R L / W$				
X↓, α→	2.50	4.00	5.50	7.00	X↓, α→	2.50	4.00	5.50	7.00

Page 91:

$$P_p / P_R = 6.46 [W / (L\lambda)]^{0.62} f^{2.47} V_B^{0.53} \quad (7-26)$$

Line 6, from bottom of page:

version of Eq. (7-23) to ascertain the performance of our pedal driven

Line 3, from bottom of page:

constant $\alpha = 2.5$; the performance dead down wind could actually be

Page 93:

$$\text{mpg} = 2.94 \times 10^6 \frac{f^{2.47}}{V_B^{1.47} [W/L]^{0.379} \lambda^{0.621}} \quad (7-27)$$

Page 97:

Beginning after (8-1):

where A_F is the area of the foil. A foil of infinite length operating in an

Beginning after (8-2):

where ϕ_T is the angle of attack in radians measured from the angle of zero

Page 107:

Second paragraph, line one:

Surface-piercing hydrofoils may be monoplanar or multiplanar as shown in

Page 111:

$$F_x h + \frac{1}{2} F_1 L = \frac{1}{2} F_2 L \quad (8-19)$$

Page 127:

$$\sigma_{\max} = W \ell h / I \quad (9-1)$$

where W is the weight of the boat, ℓ is the length of the beam, h is the half-

$$\sigma_{\max} = \frac{1}{2}W\ell/(ah\tau) \quad (9-4)$$

The weight of the beam is given approximately by

$$W_B = 2\ell (a + 2h) \tau v \quad (9-5)$$

Beginning with line 13, from bottom of page:
we find

$$W_B/W = \ell^2 (v/\sigma_{\max}) (a + 2h) / (ah)$$

or

$$\ell = \left\{ (W_B/W) (\sigma_{\max}/v) [ah / (a + 2h)] \right\}^{1/2} \quad (9-6)$$

Page 135:

Line 13, from top of page:

windward foil with force output F_3 and a fixed dihedral angle θ_3 . This

Line 7, from bottom of page:

in both cases. The dihedral angle on the forward lee foil is about 28° ; this

Page 139:

Second paragraph, first line:

Chapters 4, 5, and 7 are concerned with alternative means to harness the

Page 141:

Second paragraph, line 5:

distance between the two bearings must be at least eight percent of the mast

Page 145:

Second paragraph, line 7:

polar curves of $V_B(\gamma, V_T)$ with confidence. For the calculation, the curve of